

## Reproducibility plan for <paper title>

Reproducibility levels: as per <https://cgranell.github.io/rrp/assessment.html>

0 – undocumented; 1 – documented (i.e. recreatable); 2 – available; 3 – available & open (long term, with DOI)

### Data

Dataset (add more rows as needed)	Current reproducibility level and reasoning why	Planned measures for improvement and target reproducibility level
<i>E.g., OpenStreetMap Nederland from Geofabrik as base data</i>	<i>2 because it is publicly available with a clear license and URL</i>	<i>None planned, because 2 is considered sufficient</i>

### Methods

Method (add more rows as needed)	Current reproducibility level and reasoning why	Planned measures for improvement and target reproducibility level
<i>E.g., K-means clustering for earthquake epicenters</i>	<i>0 because parameters (e.g. K) and software environment not yet defined</i>	<i>Publish Python code for analysis on Github, target level 2 (no DOI, but open source, publicly available)</i>

### Results

Results (add more rows as needed)	Current reproducibility level and reasoning why	Planned measures for improvement and target reproducibility level
<i>E.g., choropleth maps showing priority areas for intervention</i>	<i>0 because nothing is yet defined</i>	<i>Publish interactive web map including underlying data set, target level 2 (no DOI, but users can investigate outcomes fully, publicly available)</i>

Computational environment	Yes/no	Planned measures for improvement